

CUDA and GPU Memory Systems

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<http://www.ks.uiuc.edu/Research/gpu/>

GPGPU 2015: Advanced Methods for Computing with CUDA,

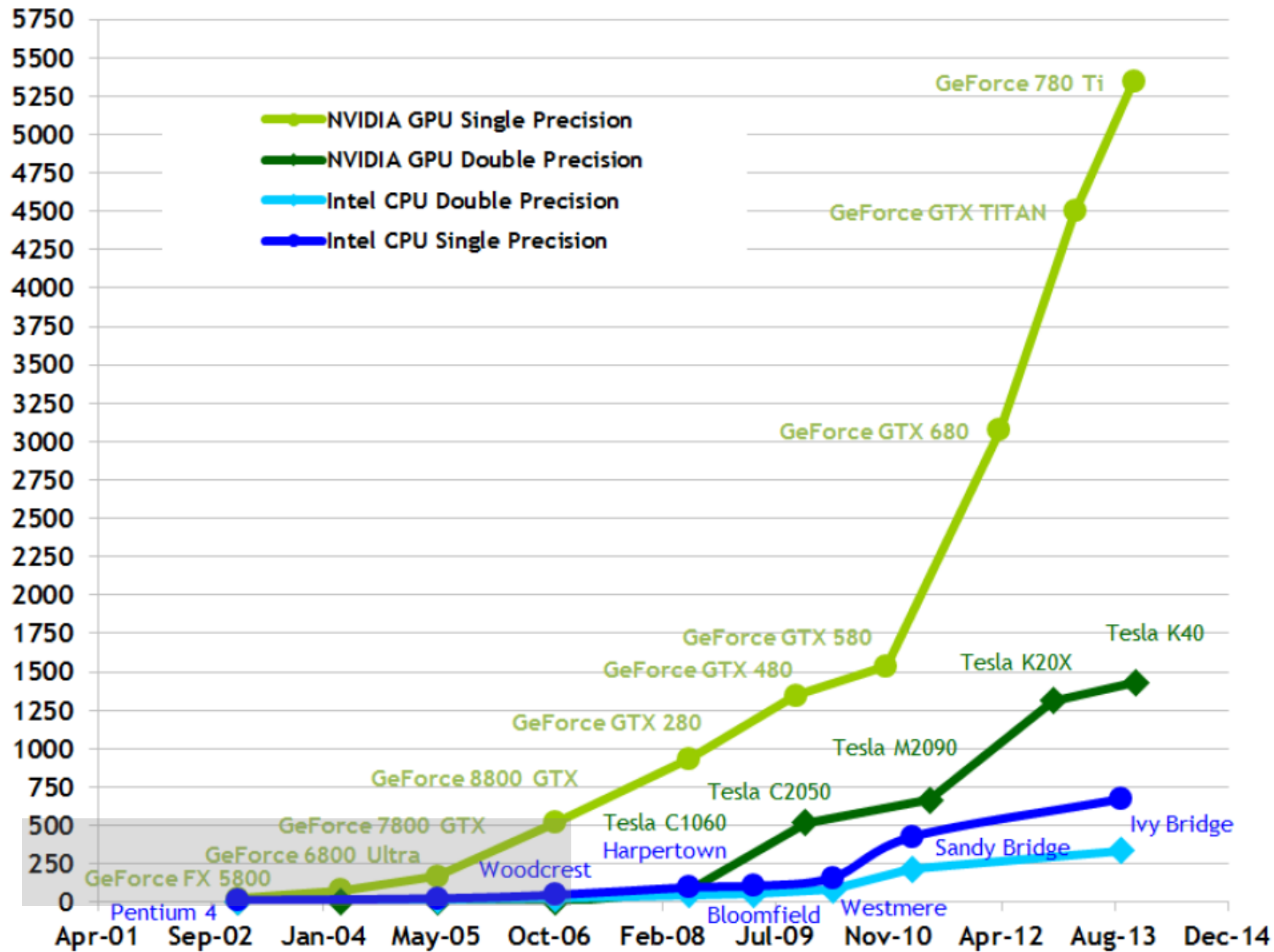
University of Cape Town, April 2015



GPU On-Board Global Memory

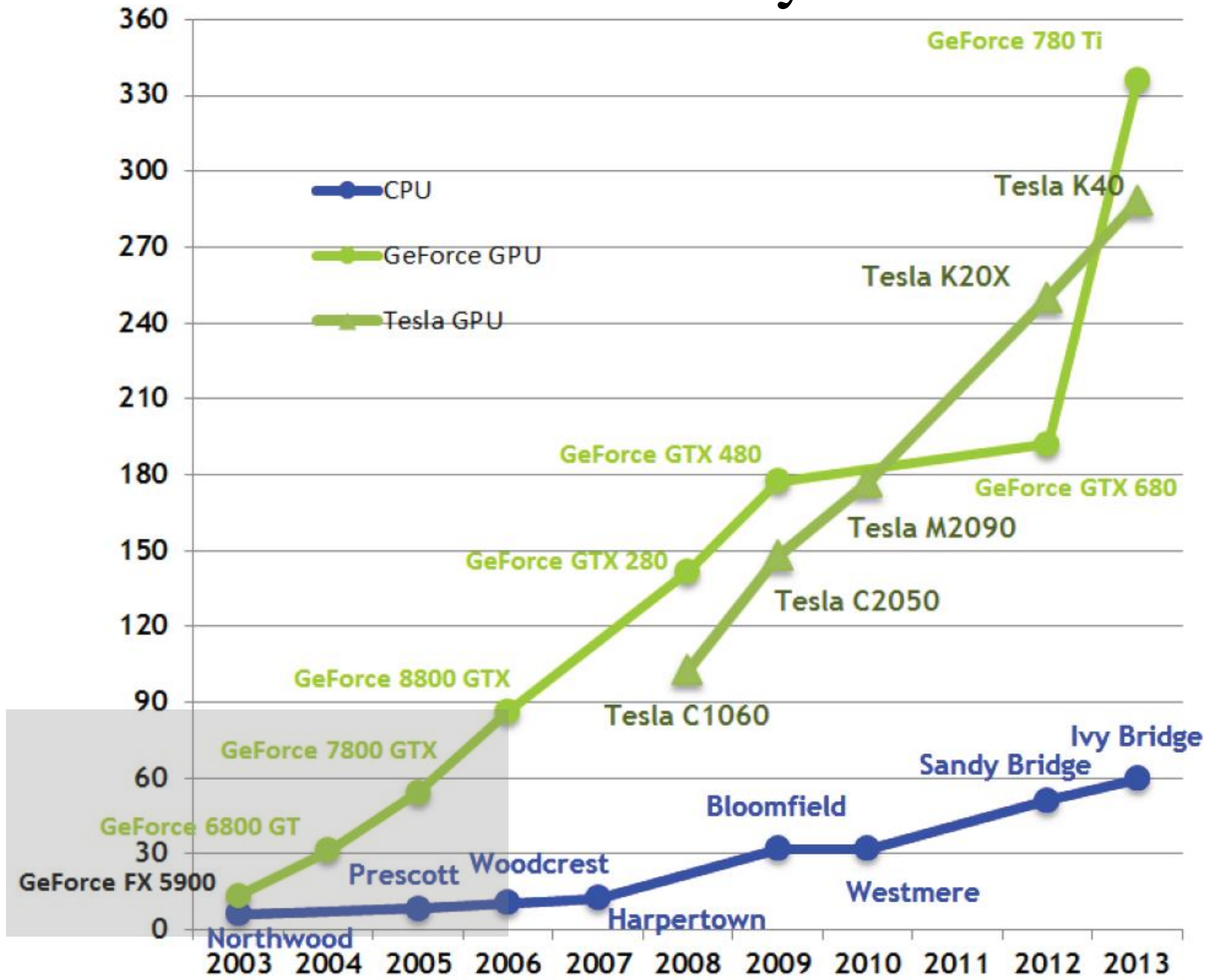
- GPU arithmetic rates dwarf memory bandwidth
- For Kepler K40 hardware:
 - ~4.3 SP TFLOPS vs. ~288 GB/sec
 - The ratio is roughly **60 FLOPS per memory reference** for single-precision floating point
- Peak performance achieved with “**coalesced**” memory access patterns – patterns that result in a single hardware memory transaction for a SIMD “**warp**” – a **contiguous group of 32 threads**

Peak Arithmetic Performance Trend



Peak Memory Bandwidth Trend

Theoretical GB/s



Memory Coalescing

- Oversimplified explanation:
 - Threads in a warp perform a read/write operation that can be serviced in a single hardware transaction
 - Rule vary slightly between hardware generations, but new GPUs are much more flexible than old ones
 - If all threads in a warp read from a contiguous region that's 32 items of 4, 8, or 16 bytes in size, that's an example of a coalesced access
 - Multiple threads reading the same data are handled by a hardware broadcast
 - Writes are similar, but multiple writes to the same location yields undefined results

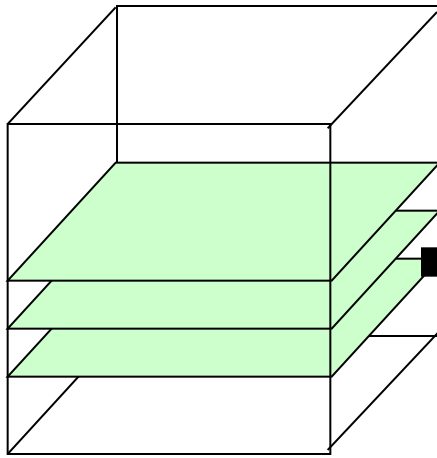
Using the CPU to Optimize GPU Performance

- GPU performs best when the work evenly divides into the number of threads/processing units
- Optimization strategy:
 - Use the CPU to “*regularize*” the GPU workload
 - Use fixed size bin data structures, with “empty” slots skipped or producing zeroed out results
 - Handle exceptional or irregular work units on the CPU; GPU processes the bulk of the work concurrently
 - On average, the GPU is kept highly occupied, attaining a high fraction of peak performance

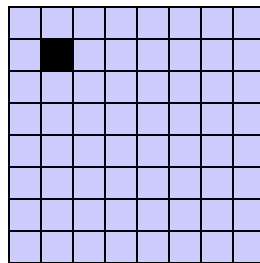
CUDA Grid/Block/Thread Decomposition

**1-D, 2-D, or 3-D
Computational Domain**

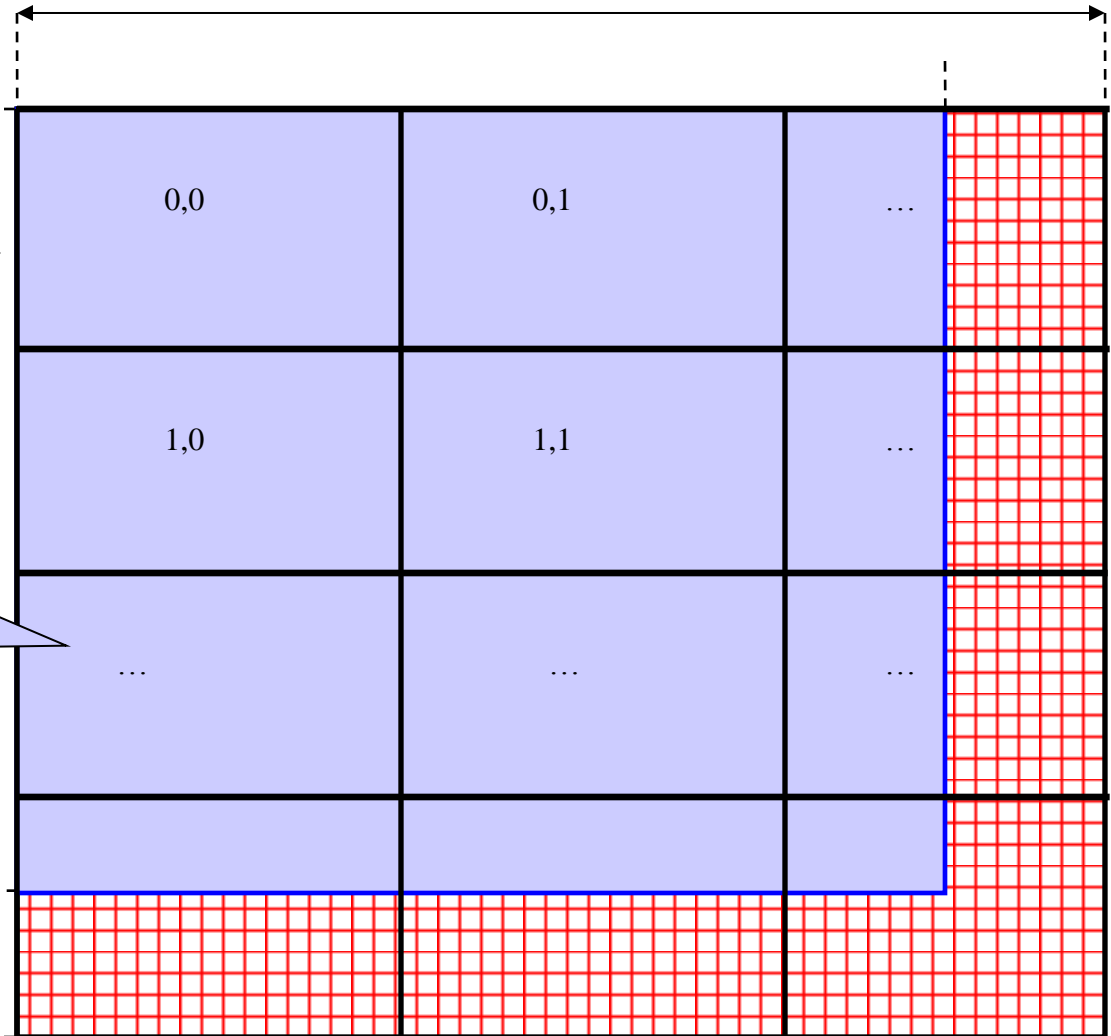
**1-D, 2-D, or 3-D (SM \geq 2.x)
Grid of thread blocks:**



**1-D, 2-D, 3-D
thread block:**



Padding arrays out to full blocks
optimizes global memory performance
by guaranteeing memory coalescing

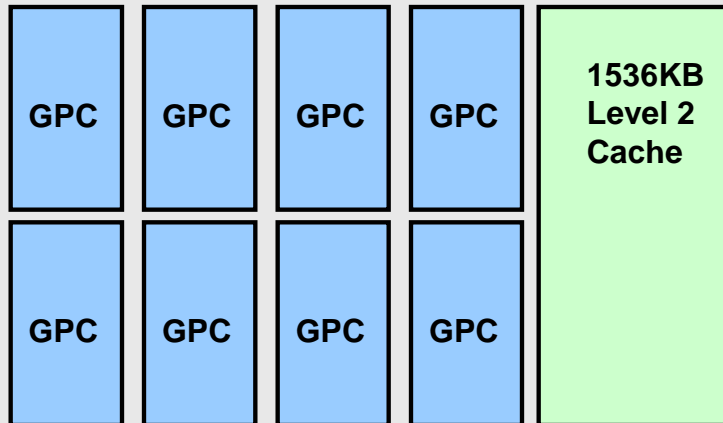


GPU On-Chip Memory Systems

- GPU arithmetic rates dwarf global memory bandwidth
- GPUs include multiple fast **on-chip** memories to help **narrow the gap**:
 - **Registers**
 - Constant memory (64KB)
 - **Shared memory (48KB / 16KB)**
 - Read-only data cache / Texture cache (~48KB)
 - Hardware-assisted 1-D, 2-D, 3-D locality
 - Hardware range clamping, type conversion, interpolation

NVIDIA Kepler GPU

3-12 GB DRAM Memory w/ ECC



Graphics Processor Cluster

SMX

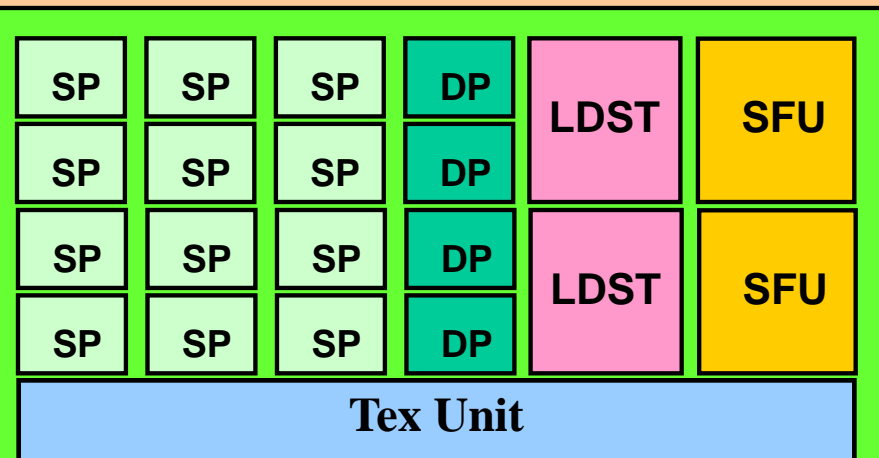
SMX

Streaming Multiprocessor - SMX

64 KB Constant Cache

64 KB L1 Cache / Shared Memory

48 KB Tex + Read-only Data Cache

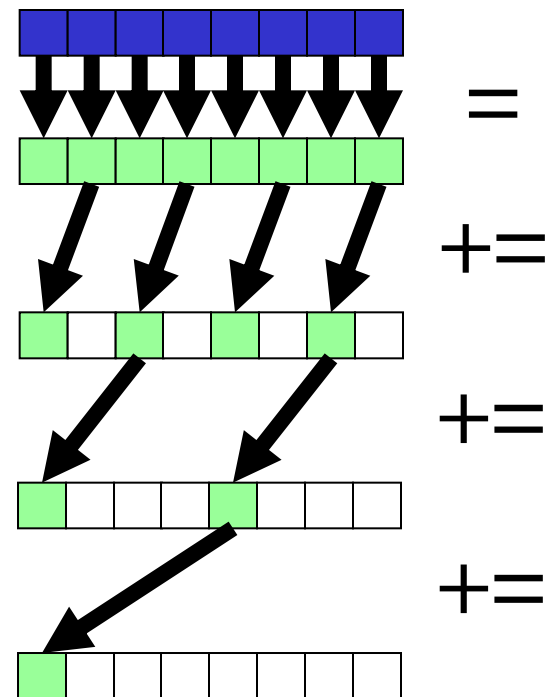


16 × Execution block =
192 SP, 64 DP,
32 SFU, 32 LDST

Communication Between Threads

- Threads in a warp or a thread block can write/read shared memory, global memory
- Barrier synchronizations, and memory fences are used to ensure memory stores complete before peer(s) read...
- Atomic ops can enable limited communication between thread blocks

Shared Memory Parallel Reduction Example



Avoiding Shared Memory Bank Conflicts: Array of Structures (AOS) vs. Structure of Arrays (SOA)

- AOS:

```
typedef struct {  
    float x;  
    float y;  
    float z;  
} myvec;  
  
myvec aos[1024];  
  
aos[threadIdx.x].x = 0;  
aos[threadIdx.x].y = 0;
```

- SOA

```
typedef struct {  
    float x[1024];  
    float y[1024];  
    float z[1024];  
} myvecs;  
  
myvecs soa;  
  
soa.x[threadIdx.x] = 0;  
soa.y[threadIdx.x] = 0;
```

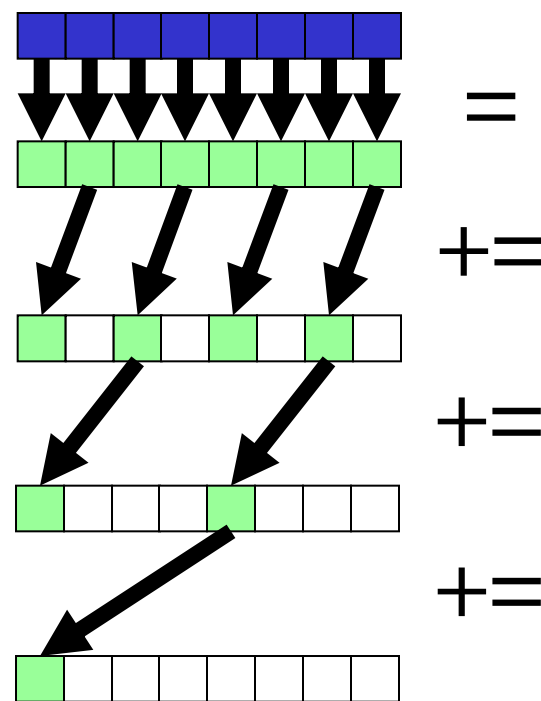
Use of Atomic Memory Ops

- Independent thread blocks can access shared counters, flags safely without deadlock when used properly
 - Allow a thread to inform peers to early-exit
 - Enable a thread block to determine that it is the last one running, and that it should do something special, e.g. a reduction of partial results from all thread blocks

Communication Between Threads in a Warp

- On the recent **Kepler/Maxwell GPUs**, neighboring threads in a warp can exchange data with each other using **shuffle instructions**
- Shuffle outperforms shared memory, and leaves shared memory available for other data

Intra-Warp Parallel Reduction with Shuffle, No Shared Memory Use



Avoid Output Conflicts, Conversion of Scatter to Gather

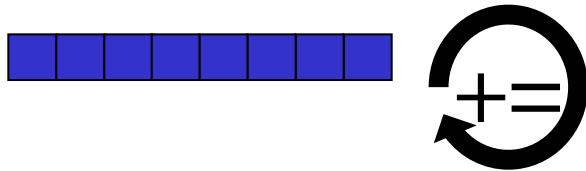
- Many CPU codes contain algorithms that “scatter” outputs to memory, to reduce arithmetic
- Scattered output can create bottlenecks for GPU performance due to bank conflicts
- On the GPU, it’s often better to do **more arithmetic**, in exchange for a **regularized output pattern**, or to convert “scatter” algorithms to “gather” approaches

Avoid Output Conflicts: Privatization Schemes

- **Privatization**: use of private work areas for workers
 - Avoid/reduce the need for thread synchronization barriers
 - Avoid/reduce the need atomic increment/decrement operations during work, use **parallel reduction** at the end...
- By working in separate memory buffers, workers **avoid read/modify/write conflicts** of various kinds
- Huge GPU thread counts make it impractical to privatize data on a per-thread basis, so GPUs must use **coarser granularity: warps, thread-blocks**
- Use of the **on-chip shared memory** local to each SM can often be considered a form of privatization

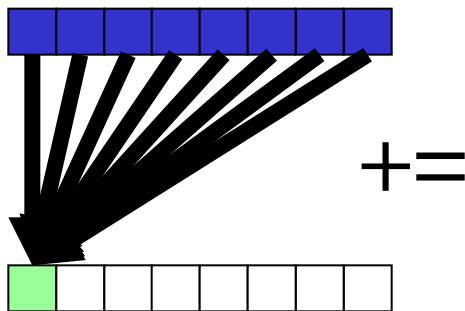
Example: avoiding output conflicts when summing numbers among threads in a block

Accumulate sums in thread-local registers before doing any reduction among threads

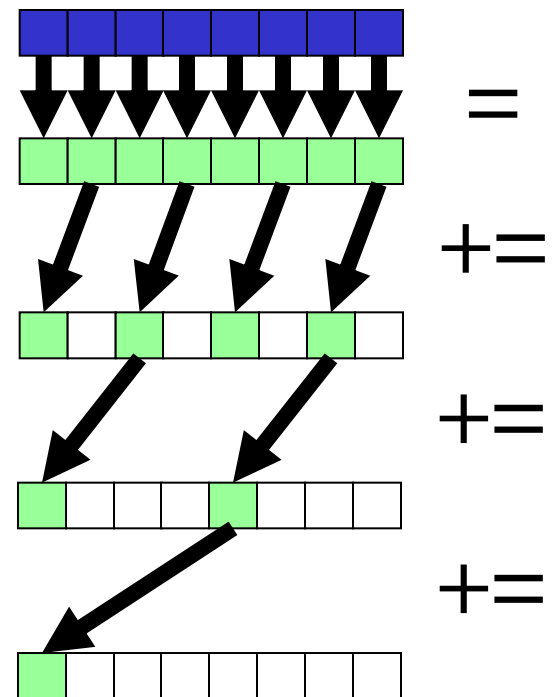


N-way output conflict:

Correct results require **costly barrier synchronizations** or **atomic memory operations ON EVERY ADD** to prevent threads from overwriting each other...



Parallel reduction: no output conflicts, $\text{Log}_2(N)$ barriers



Off-GPU Memory Accesses

- Direct access or transfer to/from host memory or peer GPU memory
 - Zero-copy behavior for accesses within kernel
 - Accesses become PCIe transactions
 - Overlap kernel execution with memory accesses
 - faster if accesses are coalesced
 - slower if not coalesced or multiple writes or multiple reads that miss the small GPU caches
- Host-mapped memory
 - `cudaHostAlloc()` – allocate GPU-accessible host memory

Off-GPU Memory Accesses

- Unified Virtual Addressing (UVA)
 - CUDA driver ensures that all GPUs in the system use unique non-overlapping ranges of virtual addresses which are also distinct from host VAs
 - CUDA decodes target memory space automatically from the pointer
 - Greatly simplifies code for:
 - GPU accesses to mapped host memory
 - Peer-to-Peer GPU accesses/transfers
 - MPI accesses to GPU memory buffers
- Leads toward Unified Virtual Memory (UVM)

Page Locked (Pinned) Host Memory

- Allocates host memory that is marked unmoveable in the OS VM system, so hardware can safely DMA to/from it
- Enables Host-GPU DMA transfers that approach full PCIe bandwidth:
 - PCIe 2.x 6 GB/s
 - PCIe 3.x 12 GB/s
- Enables full overlap of Host-GPU DMA and simultaneous kernel execution
- Enables simultaneous bidirectional DMAs to/from host

Multi-GPU Cards Will Become More Common

- Peak memory bandwidth bound by area / perimeter of the GPU processor die, pin count, etc.
- Apps bound by memory bandwidth can be better served by multi-GPU systems, multi-GPU cards
- Multi-GPU cards will likely become more common as die-stacked memory and fast GPU-to-GPU links (e.g. announced NVLink) arrive



GeForce Titan Z



Tesla K10



GeForce GTX 690

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GPU Computing Publications

<http://www.ks.uiuc.edu/Research/gpu/>

- **Runtime and Architecture Support for Efficient Data Exchange in Multi-Accelerator Applications** Javier Cabezas, Isaac Gelado, John E. Stone, Nacho Navarro, David B. Kirk, and Wen-mei Hwu. IEEE Transactions on Parallel and Distributed Systems, 26(5):1405-1418, 2015.
- **Unlocking the Full Potential of the Cray XK7 Accelerator** Mark Klein and John E. Stone. Cray Users Group, Lugano Switzerland, May 2014.
- **Simulation of reaction diffusion processes over biologically relevant size and time scales using multi-GPU workstations** Michael J. Hallock, John E. Stone, Elijah Roberts, Corey Fry, and Zaida Luthey-Schulten. Journal of Parallel Computing, 40:86-99 2014.
- **GPU-Accelerated Analysis and Visualization of Large Structures Solved by Molecular Dynamics Flexible Fitting** John E. Stone, Ryan McGreevy, Barry Isralewitz, and Klaus Schulten. Faraday Discussions, 169:265-283, 2014.
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- **Early Experiences Scaling VMD Molecular Visualization and Analysis Jobs on Blue Waters.** J. E. Stone, B. Isralewitz, and K. Schulten. Extreme Scaling Workshop (XSW), pp. 43-50, 2013.
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- **GPU-accelerated molecular modeling coming of age.** J. Stone, D. Hardy, I. Ufimtsev, K. Schulten. *J. Molecular Graphics and Modeling*, 29:116-125, 2010.
- **OpenCL: A Parallel Programming Standard for Heterogeneous Computing.** J. Stone, D. Gohara, G. Shi. *Computing in Science and Engineering*, 12(3):66-73, 2010.



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- **GPU Clusters for High Performance Computing.** V. Kindratenko, J. Enos, G. Shi, M. Showerman, G. Arnold, J. Stone, J. Phillips, W. Hwu. *Workshop on Parallel Programming on Accelerator Clusters (PPAC)*, In Proceedings IEEE Cluster 2009, pp. 1-8, Aug. 2009.
- **Long time-scale simulations of in vivo diffusion using GPU hardware.** E. Roberts, J. Stone, L. Sepulveda, W. Hwu, Z. Luthey-Schulten. In *IPDPS'09: Proceedings of the 2009 IEEE International Symposium on Parallel & Distributed Computing*, pp. 1-8, 2009.
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